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8 **Abstract**

9 Climate change has worsened droughts and floods, and created conditions more likely to lead
10 to pathogen contamination of surface water and groundwater. Thus, there is a growing need to
11 disinfect livestock water. Ultraviolet (UV) irradiation is widely accepted as an appropriate
12 method for disinfecting livestock water, as it does not produce hazardous chemical compounds
13 and kills pathogens. However, UV-based disinfection inevitably consumes electricity, so it is
14 necessary to improve UV disinfection effectiveness. Aluminum-based reflective nanolens arrays
15 that enhanced the effectiveness of a continuous-flow ultraviolet (UV) water disinfection system
16 were developed using electrochemical and chemical processes, including electropolishing and
17 two-step anodization. A continuous UV disinfection system was custom designed and the parts
18 were produced using a three-dimensional printer. Electropolished aluminum was anodized at 40
19 and 80 V in 0.3 M oxalic acid, at 120 and 160 V in 1.0 M phosphoric acid, and at 200 and 240 V
20 in 1.5 M citric acid. The average nanolens diameters (D) of the aluminum-based reflective
21 nanolens arrays prepared using 40, 80, 120, 160, 200, and 240 V anodization were 95.44, 160.98,
22 226.64, 309.90, 296.32, and 339.68 nm, respectively. Simple UV reflection behind irradiated
23 water disinfected *Escherichia coli* O157:H7 in water more than did the non-reflective control.
24 UV reflection and focusing behind irradiated water using an aluminum-based reflective nanolens
25 array disinfected *E. coli* O157:H7 more than did simple UV reflection. Such enhancement of the
26 UV disinfection effectiveness was significantly effective when a nanolens array with D 226.64
27 nm, close to the wavelength of the irradiated UV (254 nm), was used.

28
29 **Keywords:** Nanolens array, UV inactivation, anodic aluminum oxide, livestock water
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Introduction

An adequate supply of clean and safe water is critical for producing safe and healthy livestock and poultry [1, 2]. Livestock and poultry may be given water originating from surface water (e.g., streams, rivers, lakes, etc.), rainwater, or groundwater (e.g., underground springs and wells) [3, 4]. Microbiological contamination of livestock water is highly correlated with the microbiological safety of livestock products [5, 6]. Microbiologically hazardous livestock water should be disinfected. However, the global temperature has been increasing for over 100 years [7], and the severity and likelihood of droughts and floods have increased worldwide [8]; this has reduced the surface water available for livestock, and has even caused pathogen contamination of groundwater [9]. There is a growing need to disinfect livestock water due to climate change.

Livestock water may be chlorinated, filtered, ozonated, or ultraviolet (UV)-irradiated to ensure microbiological safety. Chlorination is easy and effective, and the most common water treatment method [3]. However, chlorination produces disinfection by-products (DBPs) through the interactions of chlorine with organic matter naturally present in water. DBPs include genotoxic, mutagenic, and carcinogenic compounds such as dichloroacetic acid, chlorophenols, and trihalomethanes [10, 11]. DBPs increase the risk of various cancers in humans [12], and cause health and reproductive problems in livestock and poultry [13]. UV-based water treatment is widely accepted as an alternative to chlorination, because it effectively inactivates pathogenic microorganisms but does not require chemicals or generate DBPs [14]. UV-based water treatment is rapidly gaining popularity. The global UV disinfection equipment market was USD 1.3 billion in 2019 and is estimated to reach USD 5.7 billion by 2027, with a mean annual growth rate of 17.1% projected from 2020 to 2027 [15]. However, UV-based water treatment inevitably consumes electricity, putting economic strain on farmers and environmental burden on the climate. Therefore, it is necessary to develop an energy-efficient UV water disinfection system. Enhancing UV

disinfection effectiveness may improve the energy efficiency of UV water disinfection systems as processing capacity changes, which is the motivation for this study.

Ultraviolet is electromagnetic radiation at wavelengths of 10–400 nm and has germicidal activity. When microorganisms in water are irradiated with UV, the microbial DNA is damaged, which hinders RNA synthesis and DNA replication, and inactivates the microorganisms. The germicidal activity of UV is directly related to the UV dose, which depends on the period of UV irradiation [16, 17]. Longer exposure to UV causes greater DNA damage and decreased viability of *Escherichia coli* [17]. The total UV dose received by microorganisms in water can be increased (without supplying additional UV) by placing a reflector behind the object to be irradiated; this enhances UV disinfection effectiveness [18, 19]. In addition, UV, like other light, can be focused to a point by a lens. Microorganisms are readily inactivated by focused UV [19]. Therefore, we supposed that UV water disinfection effectiveness would be enhanced if UV was reflected and focused on microorganisms by a reflector placed behind the water. When developing reflective concave lenses to enhance UV water disinfection effectiveness, we considered the size and distribution of microorganisms in water. Microorganisms that contaminate water include viruses (20–1,000 nm in size), bacteria (1–8 μm), and protozoa (10–50 μm) and are randomly distributed in water [20, 21]. We hypothesized that an array of reflective concave lenses with a submicrometer inter-lens distance would allow UV light reflected behind the water to be focused on randomly distributed microorganisms, enhancing the UV disinfection effectiveness.

Aluminum is highly reflective, but reflectivity is affected by surface roughness. An aluminum surface can be electropolished to a mirror-like state as aluminum is electrochemically reactive [22]. In addition, via anodization, the aluminum surface can be fabricated into a nanoporous structure (with hexagonally arranged nanopores) by applying an electrical voltage under acidic conditions. In this process, when aluminum is oxidized, an aluminum oxide layer develops on the surface but

is then partially corroded to produce a nanoporous aluminum oxide layer (Fig 1) [23]. The anodic aluminum oxide (AAO) layer consists of hexagonal AAO cells (Fig 1B). A cylindrical nanopore with a round bottom forms in the center of each AAO cell [24]. The sizes of the AAO cells and nanopores depend on the electrolyte and voltage used for anodization [25]. Aluminum anodization yields ordered porous AAO layers of various cell diameters under different conditions, for example, oxalic acid at 40–70 V (50–100 nm) [26], phosphoric acid at 100–195 V (250–380 nm) [25], and citric acid at 200–370 V (500 nm) [27, 28]. Beneath the AAO cell, the aluminum is concave. Thus, a regularly arranged nanolens array can be obtained by removing the AAO layer in a chemical solution selectively reactive to AAO (Fig 1C).

We postulated that UV disinfection effectiveness could be enhanced using aluminum-based reflective nanolens arrays. In particular, we investigated the effects of the array lens diameter (D) on UV disinfection. Aluminum-based reflective nanolens arrays with D values of 95–330 nm were developed via electrochemical and chemical processes. A continuous-flow UV disinfection system that placed an aluminum-based reflective nanolens array in direct contact with water was custom-designed and -developed. *E. coli* O157:H7-inoculated water was treated with the custom-made system equipped with an aluminum-based reflective nanolens array, and viable *E. coli* O157:H7 were counted. Based on the UV disinfection test, we explored the effects of D on UV disinfection and nanolens arrays that enhanced the effectiveness of the UV water disinfection system.

Materials and Methods

Materials

Aluminum sheets (alloy 1050), quartz plates, and graphite cathodes were purchased from Kwang-Lim Metal (Hwaseong-si, Gyeonggi-do, Korea), Seoul Special Glass (Namyangju-si, Gyeonggi-do, Korea), and Moon Hwa Titan Art (Incheon, Korea), respectively. Acetone (all v/v)

(99.8%), chromic acid (99%), citric acid (99.5%), ethanol (99.5%), and perchloric acid (90%) were purchased from Daejung Chemicals and Metals (Siheung-si, Gyeonggi-do, Korea). Ethylene glycol (99.5%) and oxalic acid (99.5%) were purchased from Junsei Chemical (Tokyo, Japan). Phosphoric acid (85%) was purchased from Sigma-Aldrich (St. Louis, MO, USA). Luria-Bertani (LB) broth and LB agar were purchased from BD (Sparks, MD, USA). Hexagonal head bolts (size: M5 × 40 mm) and butterfly nuts (size: M5) were purchased from a local market.

Methods

Preparation of nanolens arrays

Nanolens arrays were prepared via two-step anodization with subsequent chemical dissolution of AAO. Industrial-grade 180 × 30 × 1 mm aluminum sheets were cleaned with acetone, annealed at 400°C for 2 h, and cooled slowly to ambient temperature. The aluminum was electropolished by applying 42 V for 40 s at 5°C in a solution of ethanol, ethylene glycol, perchloric acid, and distilled water (DW) (71:10:7:12 by volume) using an electrochemical reactor featuring a DC power supply (TEX-300; Toyotech, Incheon, Korea), an anode clamp, a graphite cathode (180 × 30 × 4 mm), a jacketed beaker, and a circulating constant temperature bath (CCA-112A; Eyela, Tokyo, Japan). The electropolished aluminum was washed vigorously with DW and dried at 60°C.

Two-step anodization featured initial anodization followed by chemical dissolution of AAO and second anodization and dissolution steps. The electrochemical reactor described above was also used for anodization. The first anodization was conducted at 40 and 80 V in 0.3 M oxalic acid, 120 and 160 V in 1.0 M phosphoric acid, and 200 and 240 V in 1.5 M citric acid for 20 min each. During anodization, the solution temperature was maintained below 5°C. Anodized aluminum was washed with DW, dried, placed in a solution of 0.15 M chromic acid and 0.6 M phosphoric acid for 8 h at 65°C to remove AAO, washed with DW, and dried. The second anodization was performed for 10 min using the same voltage and solution as the first anodization, and the anodized

aluminum was washed and dried. Aluminum-based reflective nanolens arrays were produced by chemically removing the AAO formed by the second anodization. The second AAO dissolution was performed as for the first dissolution. The aluminum-based reflective nanolens arrays were washed with DW, dried, and then kept in 99.5% (v/v) ethanol and dried. The nanolens arrays were irradiated with germicidal UV (254 nm; 8 W; G8T5; Sankyo Denski, Hiratsuka, Kanagawa, Japan) for 1 h and stored in a sterile container until use.

Nanolens array surface geometries.

The surface geometries of nanolens arrays were analyzed using a scanning probe microscope (Easyscan 2; Nanosurf AG., Liestal, Switzerland). The surface geometric parameters were obtained in tapping mode using a FortA silicon probe with a nominal spring constant of 1.6 N/m (Applied NanoStructures, Mountain View, CA, USA). Scanning probe image processor software (SPIP; Image Metrology AS., Lyngby, Denmark) was used to process surface images and obtain *D* values. The *D* values were compared by one-way analysis of variance followed by Scheffe's *post-hoc* test ($p < 0.05$) with SPSS ver. 26 software (IBM, Armonk, NY, USA).

Nanolens array-equipped continuous-flow UV water disinfection system

A nanolens array-equipped continuous-flow UV water disinfection system was designed using three-dimensional (3D) modeling software (Fusion 360; Autodesk, San Rafael, CA, USA). The system featured a quartz plate holder, a UV reactor body with liquid inlet and outlet ports, a nanolens array holder, a quartz plate (180 × 30 × 2 mm), a nanolens array, and silicone spacers (thickness 2 mm) (Figs 2A and 2B). The volumetric capacity of the system holding the water to be irradiated by UV was approximately 39 mL. The 3D models of a quartz plate holder, a UV reactor body, and a nanolens array holder were sent to an on-demand 3D printing service company (Crello, Seoul, Korea) and printed using acrylonitrile butadiene styrene employing a stereolithographic 3D

printer (the details of the 3D printing conditions were not provided by the company). All components were maintained in 99.5% (v/v) ethanol for 1 h, dried, irradiated with germicidal UV for 1 h, and stored in a sterile container until use. Before the UV disinfection test, the UV disinfection system was assembled using hexagon head bolts and butterfly nuts (Fig 2C).

Preparation of pathogen-contaminated water

E. coli O157:H7 ATCC 35150 (American Type Culture Collection, Rockville, MD, USA) served as a model water contaminant. The *E. coli* O157:H7-contaminated water was freshly prepared before the UV disinfection test. *E. coli* O157:H7 was cultured in LB broth. Cultures were centrifuged at $5,000 \times g$ for 20 min. The cell pellet was collected, washed with sterilized DW, resuspended in sterilized DW, and diluted to 5–6 log CFU mL⁻¹.

UV disinfection test

The UV disinfection system featuring an aluminum-based reflective nanolens array was connected to a peristaltic pump (PL-PP150D; Poong Lim, Seoul, Korea) using tubing. The system was placed on a jack lift table and covered with a custom-made UV safety box with a UV lamp slot. A germicidal UV lamp (254 nm; 8 W; G8T5; Sankyo Denski) was mounted on the slot. The distance between the UV lamp and the quartz plate of the UV disinfection system was adjusted to 65 mm, corresponding to a UV intensity of 2.072 mW cm⁻². The UV intensity at 254 nm was measured using a UV radiometer (VLX-3, Vilber Lourmat, Marine, France) fitted with a CX-254 sensor (Vilber Lourmat). *E. coli* O157:H7-contaminated water was fed to the system as UV was irradiated. Water from the system was collected, diluted, and plated onto LB agar plates. Viable *E. coli* O157:H7 numbers were enumerated after incubation of the LB agar plates at 37°C for 24 h. A graphite plate (180× 30× 4 mm) served as a control. To avoid unwanted photochemical reactions between UV and the graphite plate, a quartz plate (180× 30 × 2 mm) was placed over the graphite

plate. The UV disinfection test was performed in triplicate, once each for three aluminum-based reflective nanolens arrays prepared under identical conditions. The numbers of viable *E. coli* O157:H7 after UV treatment were compared by one-way analysis of variance followed by Tukey's *post-hoc* test ($p < 0.05$) with SPSS ver. 26 software.

Results and Discussion

Development of aluminum-based reflective nanolens arrays

The aluminum used (alloy 1050; aluminum purity 99.5%) was provided in a mechanically finished form. Electropolishing smoothed the rough aluminum surface to a mirror-like surface (Figs. 3A and 3B). Via anodization at 120 V in 1.0 M phosphoric acid, AAO developed as the aluminum was partially dissolved, and a nanoporous AAO layer formed on the surface (Fig. 3C). A nanolens array was obtained by removing the AAO (Fig. 3D). A second anodization followed by AAO removal was also performed. Finally, the nanolens arrays were obtained (Fig. 4). The arrays prepared via two-step anodization evidenced more ordered structures than those after one-step anodization (Figs. 3D and 4C). Thus, nanolens arrays prepared via two-step anodization were used for further study.

The average D values of arrays prepared via 40, 80, 120, 160, 200, and 240 V anodization were 95.44, 160.98, 226.64, 309.90, 296.32, and 339.68 nm, respectively (Fig. 5). Although the anodization voltage was higher, the D of the nanolens array prepared via 200 V anodization was not greater than that after 160 V anodization (Fig. 5). The D values we obtained were smaller than those reported previously [25, 27, 28]. We could not raise the anodization voltage to above 80 V in 0.3 M oxalic acid, above 160 V in 1.0 M phosphoric acid, or above 240 V in 1.5 M citric acid because the solution temperatures increased to levels that created burn defects. The cathode (graphite)-to-anode area ratio for the anodization in this study was approximately unity to facilitate

uniform nanolens array fabrication. The cathode-to-anode area ratio affects the local electrical current density on AAO during anodization [29]. Higher cathode-to-anode ratios indicate greater local electrical current densities and larger AAO cells [29, 30]. The differences in the D values between the present and other studies may be attributable to differences in the cathode-to-anode area ratios.

Aluminum-based nanolens arrays enhancing UV disinfection effectiveness

UV irradiation becomes more intense as the distance between the UV lamp and the irradiated body decreases. The closest distance between the UV lamp and the quartz plate of the UV disinfection system was 8 mm, at which point the UV intensity was 7.452 mW cm^{-2} . No viable *E. coli* O157:H7 were found after the UV disinfection test under any conditions when the UV disinfection test was performed at 8 mm. The distance between the UV lamp and the quartz plate was adjusted to 65 mm (UV intensity 2.075 mW cm^{-2}), and we performed UV disinfection tests of *E. coli* O157:H7-contaminated water flowing into the system at 1.5, 2, and 4 mL s^{-1} , which enabled us to obtain statistically significant results.

The UV energy imparted to the system should be equivalent when the control (graphite plate), electropolished aluminum, and aluminum-based reflective nanolens arrays were present. Graphite efficiently absorbs light, especially UV light [31]. Thus, the differences in UV disinfection results were attributable to UV reflection and focusing (Fig. 6). The *E. coli* O157:H7 was inactivated, and the count decreased from 5.74 to $2.69 \text{ log CFU mL}^{-1}$ when UV irradiation was delivered at an *E. coli* O157:H7-contaminated water at 2 mL s^{-1} (Fig. 6A). After disinfection using the electropolished aluminum-equipped UV disinfection system (flow rate 2 mL s^{-1}), the *E. coli* O157:H7 number fell to $2.00 \text{ log CFU mL}^{-1}$, significantly different from the control value (Fig. 6A). The total UV energy reaching *E. coli* O157:H7 in the system equipped with electropolished aluminum might have been greater than that of the control because the *E. coli* O157:H7 numbers

fell more when the electropolished aluminum was employed. The *E. coli* O157:H7 level further decreased when aluminum-based reflective nanolens arrays (rather than electropolished aluminum) were used (Fig. 6A). In particular, after UV disinfection at 2 mL s⁻¹ using nanolens arrays prepared via 80, 120, and 200 V anodization, the *E. coli* O157:H7 levels decreased from 5.74 to 1.64, 1.36, and 1.74 log CFU mL⁻¹, respectively (Fig. 6A). As no significant difference was apparent (Fig. 6A), the UV disinfection of nanolens arrays prepared via 80, 120, and 200 V anodization were tested at a flow rate of 4 mL s⁻¹ (Fig. 6B). The *E. coli* O157:H7 numbers fell maximally when arrays prepared via 120 V anodization were used, with significantly lower numbers than those of 80 and 200 V anodization (Fig. 6B). No viable *E. coli* O157:H7 were found after UV disinfection at a flow rate of 1.5 mL s⁻¹ using aluminum-based reflective nanolens arrays prepared via 120 V anodization. However, viable *E. coli* O157:H7 remained after disinfection at 1.5 mL s⁻¹ in the control and electropolished aluminum tests (Fig. 6C). The UV disinfection tests revealed that the UV disinfection effectiveness could be enhanced using the aluminum-based reflective nanolens arrays and might be affected by *D* (Figs. 5 and 6).

Ultraviolet reflection and focusing onto *E. coli* O157:H7 using the aluminum-based reflective nanolens arrays can enhance UV disinfection effectiveness. The surface structure of the nanolens array may affect UV disinfection. Light reflection is specular rather than diffuse when light is sent to a reflector with surface protrusions smaller than the wavelength [32]. We used a UV lamp mainly emitting 254 nm. As the *D* of the array prepared via 40 V anodization was 95.44 nm (Fig. 5), UV reflection by the nanolens array might be specular, explaining the similar UV disinfections afforded by the electropolished aluminum and the nanolens array (Fig. 6A). Also, the extent of UV disinfection using the nanolens array prepared via 240 V anodization was no better than that of the electropolished aluminum, perhaps because of excessive UV diffusion. UV disinfection effectiveness enhancement by nanolens arrays seemed to be related to the *D* value. The *D* values of arrays prepared via 160 and 200 V anodization were similar, as were the UV disinfection results

(Figs. 5 and 6A). The total UV doses to the water in the UV disinfection system might be the same when electropolished aluminum and nanolens arrays are used. However, the difference in UV disinfection was evident when the UV light was focused by the nanolens arrays. The UV light reflected by the nanolens array prepared via 120 V anodization may be better focused than that reflected by other nanolens arrays, enhancing UV disinfection effectiveness. Notably, the D of the nanolens array prepared via 120 V anodization was 226.64 nm, close to the wavelength of the irradiated UV (Figs. 5 and 6).

Conclusion

UV water disinfection is dose-dependent. UV reflection behind irradiated water using electropolished aluminum and aluminum-based reflective nanolens arrays increased the UV dose to the water and enhanced the disinfection effectiveness compared to the non-reflective control system. Although the total UV doses applied were the same when the electropolished aluminum and aluminum-based reflective nanolens arrays were used, UV focusing by the nanolens arrays enhanced the disinfection effectiveness. The enhanced UV disinfection effectiveness was significant when an aluminum-based reflective nanolens array with D similar to the wavelength of the irradiated UV (245 nm) (i.e., an aluminum-based reflective nanolens array with $D = 226.64$ nm prepared via 120 V anodization) was used. UV water disinfection system inevitably consumes electricity; therefore, the aluminum-based reflective nanolens array can be a means to save electricity consumed by the UV water disinfection system because it enhances disinfection without the need for additional electricity. Since UV rays have low penetration through organic and inorganic substances, UV irradiation is used to disinfect municipal and livestock water and sediment-removed municipal wastewater. The microbiological safety of livestock wastewater may be enhanced by applying a UV disinfection system combined with aluminum-based reflective

nanolens arrays to sediment-removed livestock wastewater. However, it may be necessary to study a scaled-up aluminum-based reflective nanolens array-equipped UV disinfection system and investigate disinfection by the scaled-up system before application in livestock farms.

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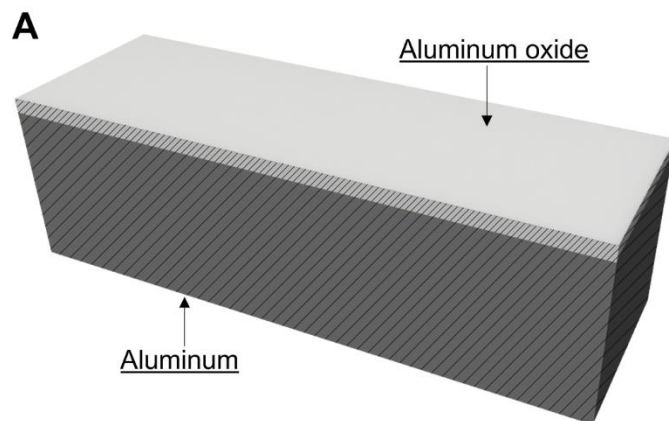
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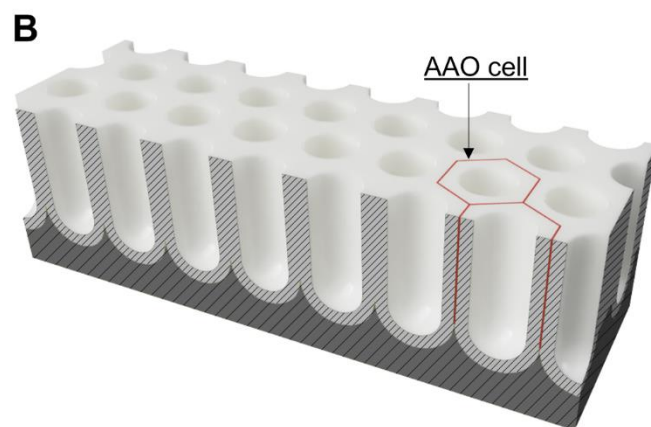
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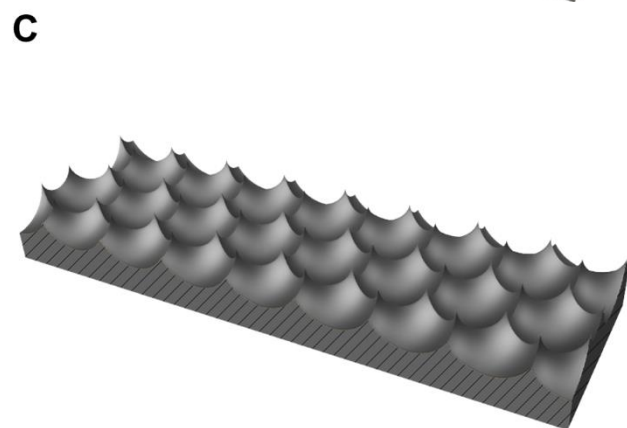
Tables and Figures



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382 Fig. 1. Schematics of (A) electropolished aluminum, (B) a porous aluminum oxide layer on
383 anodic aluminum, and (C) an aluminum-based nanolens array.

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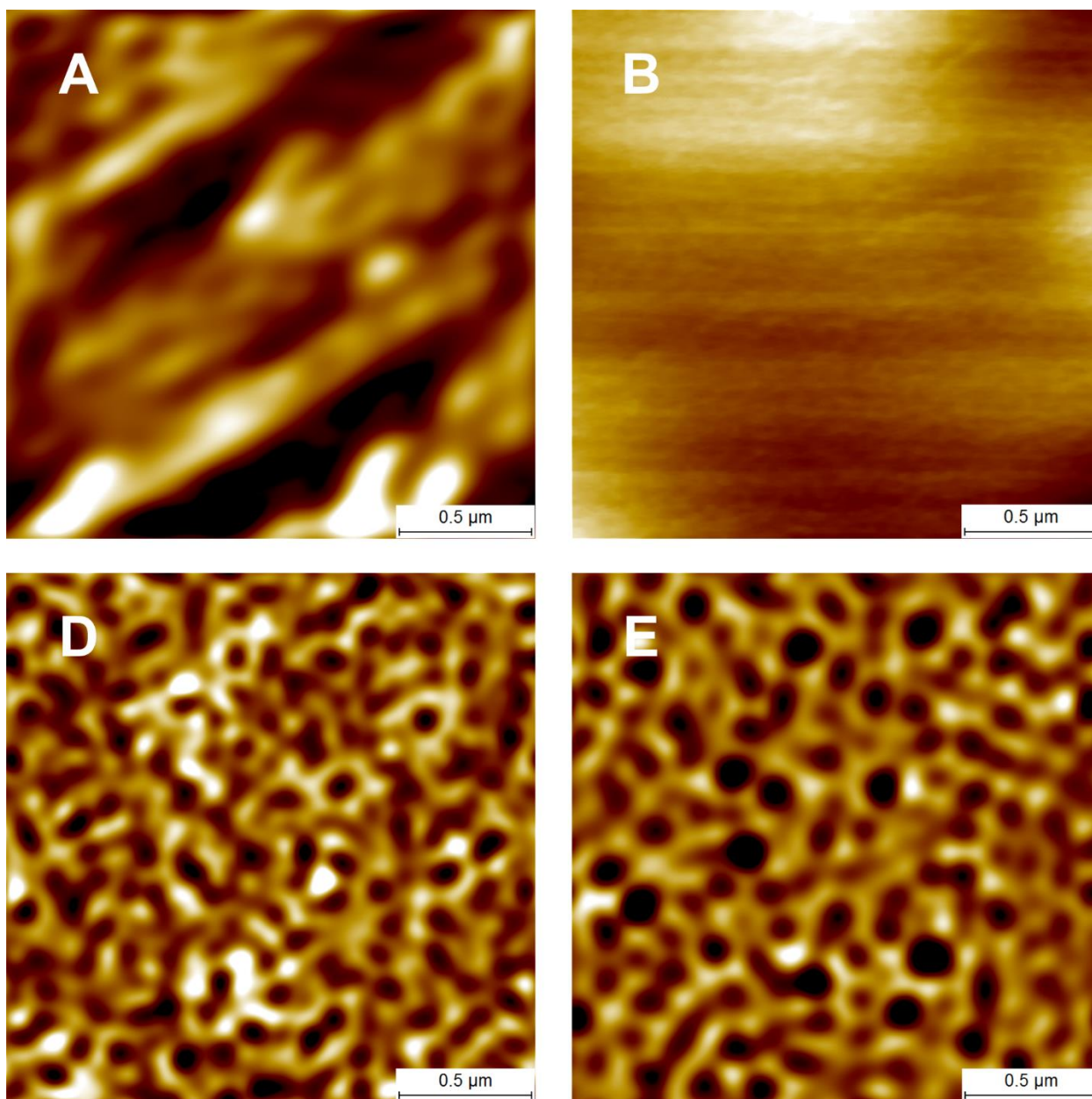


Fig. 3. SPM surface images of (A) bare aluminum, (B) electropolished aluminum, (C) anodized aluminum (after the first anodization at 120 V in 1.0 M phosphoric acid), and (D) AAO-free anodic aluminum (after the first AAO removal).

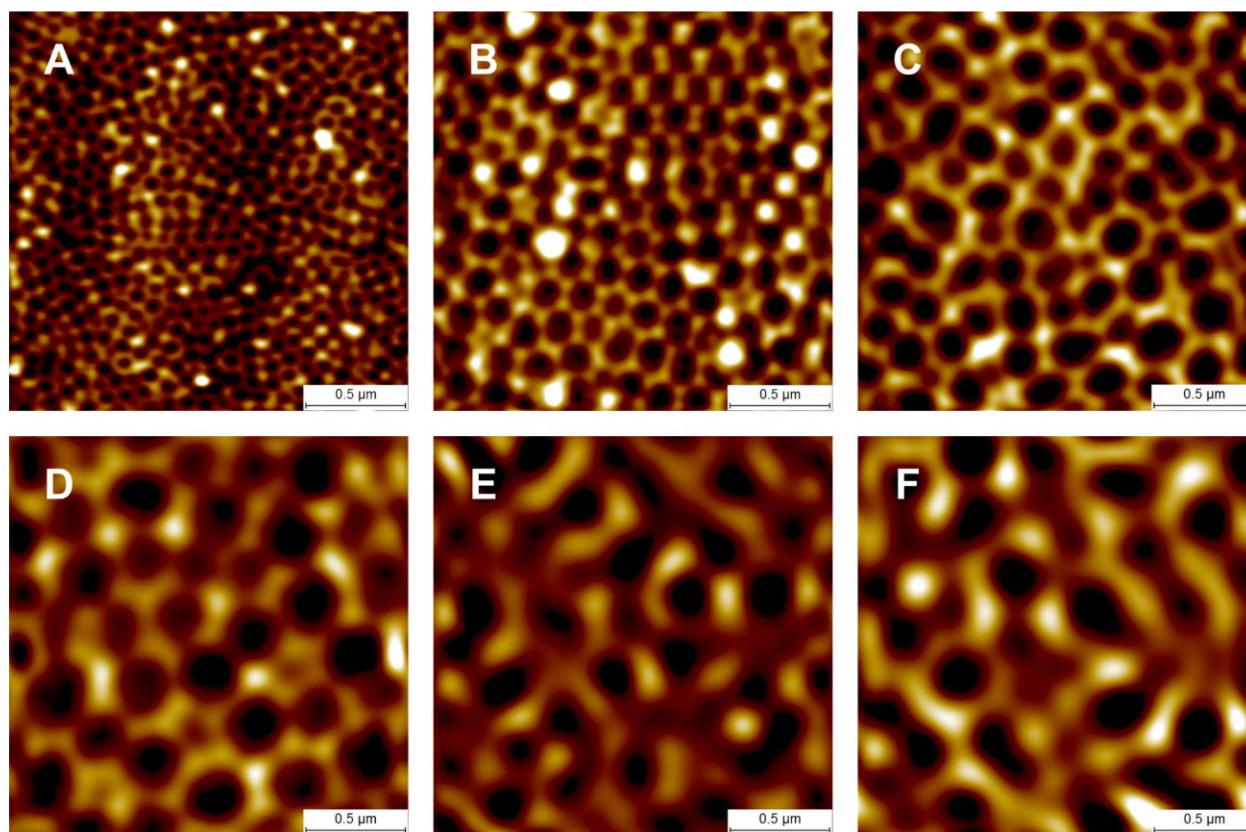


Fig. 4. SPM surface images of nanolens arrays prepared via two-step anodization at (A) 40, (B) 80, (C) 120, (D) 160, (E) 200, and (F) 240 V.

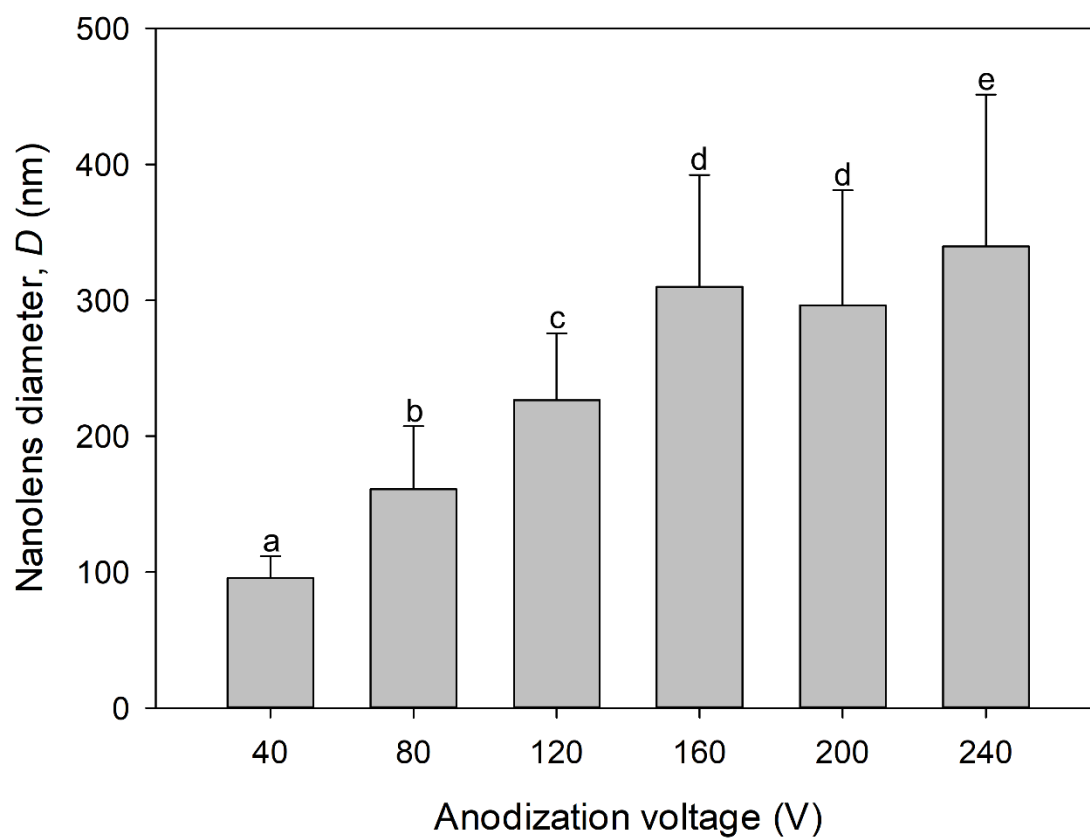


Fig. 5. The nanolens diameters (D values) of the aluminum-based, reflective nanolens arrays. Different letters above the error bars indicate significant differences ($p < 0.05$) among the groups.

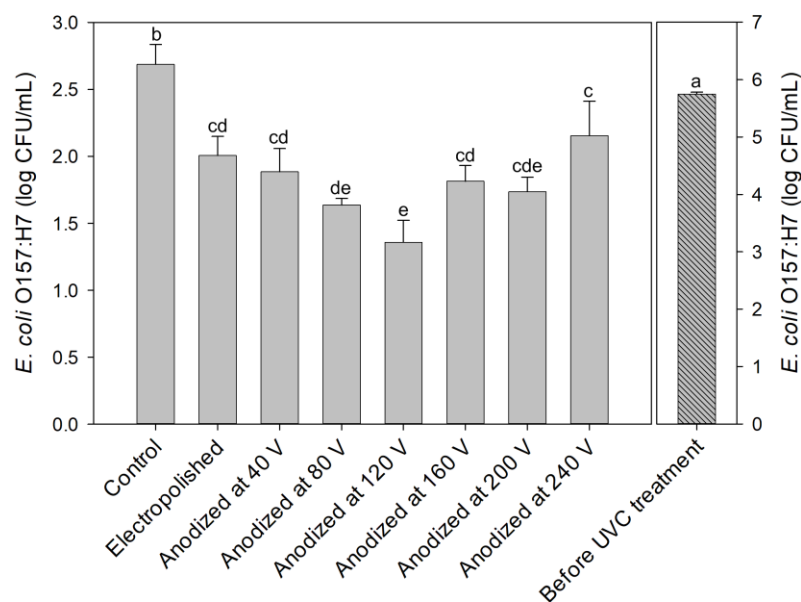
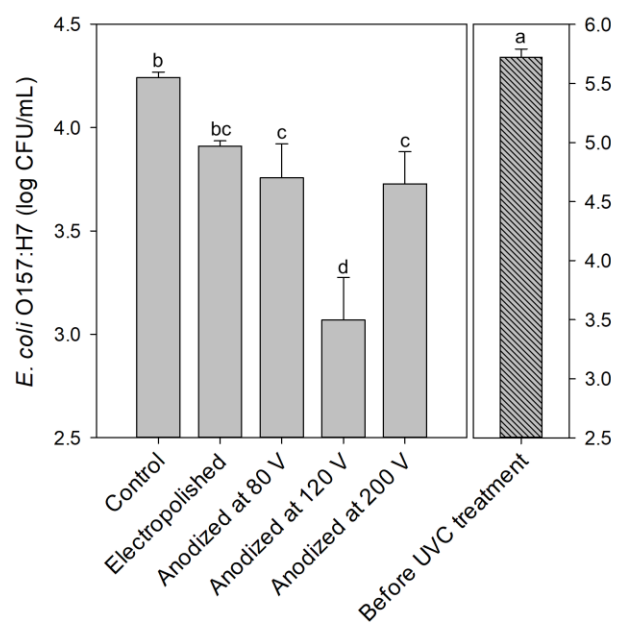
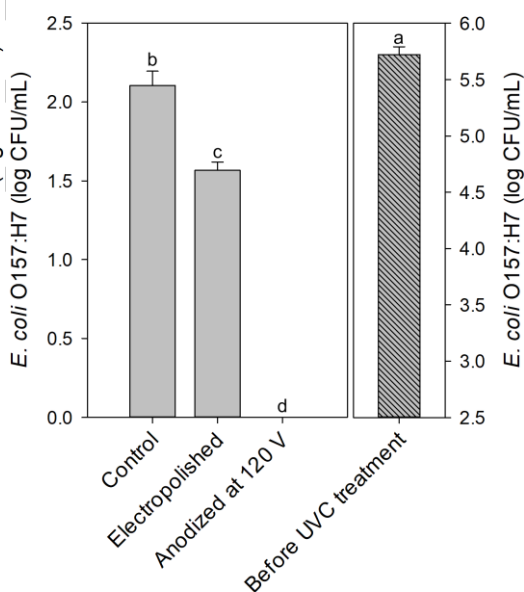
A**B****C**

Fig. 6. UV disinfection test results when aluminum-based reflective nanolens arrays were employed. The flow rates of *E. coli* O157:H7-contaminated water were (A) 2, (B) 4, and (C) 1.5 mL s⁻¹. Different letters above the error bars indicate significant differences ($p < 0.05$) among the groups.